



Almost strongly θ - e -continuous functions

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Abstract

We introduce and investigate a new class of functions called almost strongly θ - e -continuous functions, containing the classes of almost strongly θ -precontinuous [J. H. Park, S. W. Bae, Y. B. Park, Chaos Solitons Fractals, **28** (2006), 32–41], almost strongly θ -semicontinuous [Y. Beceren, S. Yüksel, E. Hatir, Bull. Calcutta Math. Soc., **87** (1995), 329–334] and strongly θ - e -continuous functions [M. Özkoç, G. Aslm, Bull. Korean Math. Soc., **47** (2010), 1025–1036]. Several characterizations concerning almost strongly θ - e -continuous functions are obtained. Also we investigate the relationships between almost strongly θ - e -continuous functions and separation axioms and almost strongly e -closedness of graphs of functions. ©2016 All rights reserved.

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1. Introduction

The concept of continuity is the most important subject in topology. In 2008, the notion of e -continuous functions was introduced and studied by Ekici [8] and in 2010, the notion of strongly θ - e -continuous functions was introduced by Özkoç and Aslm [19]. In 1984, Noiri and Kang introduced the notion of almost strong θ -continuity. Recently, three generalizations of almost strong θ -continuity are obtained by Beceren et al. [4], Park et al. [21] and Noiri and Zorlutuna [18]. The aim of this paper is to introduce and investigate a new class of functions, called almost strongly θ - e -continuous functions, which contains the classes of almost strongly θ -semicontinuous functions, almost strongly θ -precontinuous functions and strongly θ - e -continuous functions.

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We introduce and investigate some fundamental properties of almost strongly θ - e -continuous functions defined via e -open sets introduced by Ekici [8] in a topological space. It turns out that almost strong θ - e -continuity is stronger than θ - e -continuity [11] and weaker than strong θ - e -continuity [19], almost strong θ -semicontinuity [4] and almost strong θ -precontinuity [21]. Moreover, we obtain some results related to separation axioms and graphs properties.

2. Preliminaries

Throughout the paper, X and Y always mean topological spaces on which no separation axioms are assumed, unless explicitly stated. Let X be a topological space and A a subset of X . The closure and interior of A are denoted by $cl(A)$ and $int(A)$, respectively. A subset A is said to be regular open (resp. regular closed) if $A = int(cl(A))$ (resp. $A = cl(int(A))$). A point $x \in X$ is said to be δ -cluster point of A if $int(cl(U)) \cap A \neq \emptyset$ for each open neighborhood U of x . The set of all δ -cluster points of A is called the δ -closure [25] of A and is denoted by $\delta-cl(A)$. If $A = \delta-cl(A)$, then A is called δ -closed, and the complement of a δ -closed set is called δ -open. A subset A is called semiopen [12] (resp. b -open [3], e -open [8], preopen [13], α -open [15], a -open [7], β -open [1]) if $A \subset cl(int(A))$ (resp. $A \subset cl(int(A)) \cup int(cl(A))$, $A \subset cl(int_\delta(A)) \cup int(cl_\delta(A))$, $A \subset int(cl(A))$, $A \subset int(cl(int(A)))$, $A \subset int(cl(int_\delta(A)))$, $A \subset cl(int(cl(A)))$). The complement of a semiopen (resp. b -open, e -open, preopen, α -open, a -open, β -open) set is called semiclosed (resp. b -closed, e -closed, preclosed, α -closed, a -closed, β -closed). The intersection of all e -closed sets of X containing A is called the e -closure [8] of A and is denoted by $e-cl(A)$. The semiclosure, preclosure, b -closure and α -closure are similarly defined and are denoted by $scl(A)$, $pcl(A)$, $bcl(A)$ and $\alpha-cl(A)$, respectively. The union of all e -open sets of X contained in A is called the e -interior [8] of A and is denoted by $e-int(A)$. A subset A is said to be e -regular [19] if it is e -open and e -closed.

A point x of X is called an e - θ -cluster point of A if $e-cl(U) \cap A \neq \emptyset$ for every e -open set U containing x . The set of all e - θ -cluster points of A is called the e - θ -closure [19] of A and is denoted by $e-cl_\theta(A)$. A subset A is said to be e - θ -closed if $A = e-cl_\theta(A)$. The complement of an e - θ -closed set is called an e - θ -open set. Also it is noted in [19] that

$$e\text{-regular} \Rightarrow e\text{-}\theta\text{-open} \Rightarrow e\text{-open}.$$

The family of all e -open (resp. e -closed, e -regular, e - θ -open, e - θ -closed) subsets of X is denoted by $eO(X)$ (resp. $eC(X)$, $eR(X)$, $e\theta O(X)$, $e\theta C(X)$). The family of all e -open (e -closed, e -regular, e - θ -open, e - θ -closed) sets of X containing a point x of X is denoted by $eO(X, x)$ (resp. $eC(X, x)$, $eR(X, x)$, $e\theta O(X, x)$, $e\theta C(X, x)$).

Lemma 2.1 ([2]). *Let X be a topological space. If A is a preopen set in X , then $scl(A) = int(cl(A))$.*

Lemma 2.2 ([19]). *Let X be a topological space and $A \subset X$ and $\{A_\alpha \mid \alpha \in \Lambda\} \subset \mathcal{P}(X)$. Then the following statements hold:*

- (1) $A \in eO(X)$ if and only if $e-cl(A) \in eR(X)$.
- (2) A is e - θ -open in X if and only if for each $x \in A$, there exists $W \in eR(X, x)$ such that $W \subset A$.
- (3) If A_α is e - θ -open in X for each $\alpha \in \Lambda$, then $\bigcup_{\alpha \in \Lambda} A_\alpha$ is e - θ -open in X .
- (4) $A \in eR(X)$ if and only if A is e - θ -open and e - θ -closed.

Lemma 2.3 ([17]). *Let X be a topological space. Then the following statements hold:*

- (1) $\alpha-cl(V) = cl(V)$ for each β -open set V of X .
- (2) $pcl(V) = cl(V)$ for each semi-open set V of X .

Lemma 2.4. *Let A be a subset of a space X . The set A is e - θ -open in X if and only if for each $x \in A$, there exists a $U \in eO(X)$ containing x such that $x \in e-cl(U) \subset A$.*

Proof. It can be proved directly using Lemma 2.2. □

Lemma 2.5 ([11]). *Let X be a topological space and $A \subset X$. Then:*

- (1) $e-cl_\theta(X \setminus A) = X \setminus e-int_\theta(A)$.
- (2) $e-int_\theta(X \setminus A) = X \setminus e-cl_\theta(A)$.

Lemma 2.6. *Let X be a topological space. Then the following statements hold:*

- (1) $V \in \beta O(X) \Rightarrow \alpha\text{-cl}(V) \in SO(X)$.
- (2) $V \in SO(X) \Rightarrow \alpha\text{-cl}(V) = p\text{cl}(V)$.

Proof. (1) Let $V \in \beta O(X)$. We have

$$\begin{aligned} V \in \beta O(X) &\Rightarrow V \subset cl(int(cl(V))) \\ &\Rightarrow \alpha\text{-cl}(V) \subset \alpha\text{-cl}(cl(int(cl(V)))) \\ &\stackrel{\text{Lemma 2.3}}{\implies} \alpha\text{-cl}(V) \subset cl(int(cl(V))) = cl(int(\alpha\text{-cl}(V))). \end{aligned}$$

(2) Let $V \in SO(X)$. We have

$$\left. \begin{aligned} \alpha\text{-cl}(V) &= V \cup cl(int(cl(V))) \\ V \in SO(X) &\Rightarrow V \subset cl(int(V)) \end{aligned} \right\} \Rightarrow \alpha\text{-cl}(V) \subset V \cup cl(int(V)) = p\text{cl}(V) \left. \begin{aligned} V \subset X &\Rightarrow p\text{cl}(V) \subset \alpha\text{-cl}(V) \end{aligned} \right\} \Rightarrow \alpha\text{-cl}(V) = p\text{cl}(V). \quad \square$$

Lemma 2.7 ([20]). *In a space X , the intersection of an a -open set and an e -open set is an e -open set.*

3. Almost Strongly θ - e -continuous Functions

Definition 3.1. A function $f : X \rightarrow Y$ is said to be almost strongly θ - e -continuous (briefly, a.st. θ .e.c.) if for each $x \in X$ and each open set V containing $f(x)$, there exists an e -open set U in X containing x such that $f[e\text{-cl}(U)] \subset int(cl(V))$.

Theorem 3.2. *For a function $f : X \rightarrow Y$, the followings are equivalent:*

- (1) f is a.st. θ .e.c.,
- (2) for each $x \in X$ and each regular open set V containing $f(x)$, there exists an e -open set U in X containing x such that $f[e\text{-cl}(U)] \subset V$,
- (3) for each $x \in X$ and each regular open set V containing $f(x)$, there exists an e -regular set U in X containing x such that $f[U] \subset V$,
- (4) for each $x \in X$ and each regular open set V containing $f(x)$, there exists an e - θ -open set U in X containing x such that $f[U] \subset V$,
- (5) $f^{-1}[G] \in e\theta O(X)$ for every regular open set G of Y ,
- (6) $f^{-1}[F] \in e\theta C(X)$ for every regular closed set F of Y ,
- (7) $f^{-1}[G] \in e\theta O(X)$ for every δ -open set G of Y ,
- (8) $f^{-1}[F] \in e\theta C(X)$ for every δ -closed set F of Y ,
- (9) $f[e\text{-cl}_\theta(A)] \subset cl_\delta(f[A])$ for every subset A of X ,
- (10) $e\text{-cl}_\theta(f^{-1}[B]) \subset f^{-1}[cl_\delta(B)]$ for every subset B of Y ,
- (11) $e\text{-cl}_\theta(f^{-1}[cl(int(cl(B)))] \subset f^{-1}[cl(B)]$ for every subset B of Y ,
- (12) $e\text{-cl}_\theta(f^{-1}[V]) \subset f^{-1}[cl(V)]$ for every β -open set V of Y ,
- (13) $e\text{-cl}_\theta(f^{-1}[V]) \subset f^{-1}[cl(V)]$ for every semi-open set V of Y ,
- (14) $e\text{-cl}_\theta(f^{-1}[V]) \subset f^{-1}[\alpha\text{-cl}(V)]$ for every β -open set V of Y ,

- (15) $e-cl_\theta(f^{-1}[V]) \subset f^{-1}[pcl(V)]$ for every semi-open set V of Y ,
- (16) $e-cl_\theta(f^{-1}[cl(int(V))]) \subset f^{-1}[F]$ for every closed set F of Y ,
- (17) $e-cl_\theta(f^{-1}[cl(int(V))]) \subset f^{-1}[cl(V)]$ for every closed set V of Y ,
- (18) $f^{-1}[V] \subset e-int_\theta(f^{-1}[scl(V)])$ for every open set V of Y ,
- (19) $f^{-1}[V] \subset e-int_\theta(f^{-1}[int(cl(V))])$ for every preopen set V of Y ,
- (20) $f^{-1}[V] \subset e-int_\theta(f^{-1}[scl(V)])$ for every preopen set V of Y ,
- (21) $f^{-1}[V] \subset e-int_\theta(f^{-1}[int(cl(V))])$ for every open set V of Y ,
- (22) $f : X \rightarrow Y_s$ is st.θ.e.c., where Y_s denotes the semi regularization of Y .

Proof. (1) ⇒ (2): Let $x \in X$ and $V \in RO(Y, f(x))$. We have

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \\ RO(Y, f(x)) \subset \mathcal{U}(Y, f(x)) \end{array} \right\} \Rightarrow \left. \begin{array}{l} (x \in X)(V \in \mathcal{U}(Y, f(x))) \\ \text{Hypothesis} \end{array} \right\} \Rightarrow \\ \Rightarrow (\exists U \in eO(X, x))(f[e - cl(U)] \subset int(cl(V)) = V).$$

(2) ⇒ (3): Let $x \in X$ and $V \in RO(Y, f(x))$. We have

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \\ \text{Hypothesis} \end{array} \right\} \Rightarrow (\exists U' \in eO(X, x))(f[e - cl(U)] \subset V), \tag{3.1}$$

$$U' \in eO(X, x) \Rightarrow U = e - cl(U) \in eR(X, x) \tag{3.2}$$

(3.1),(3.2) ⇒ $(\exists U \in eR(X, x))(f[U] \subset V)$.

(3) ⇒ (4): Let $x \in X$ and $V \in RO(Y, f(x))$. We have

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \\ \text{Hypothesis} \end{array} \right\} \Rightarrow \left. \begin{array}{l} (\exists U \in eR(X, x))(f[U] \subset V) \\ eR(X, x) \subset e\theta O(X, x) \end{array} \right\} \Rightarrow (\exists U \in e\theta O(X, x))(f[U] \subset V).$$

(4) ⇒ (5): Let $G \in RO(Y, f(x))$ and $x \notin f^{-1}[G]$. We have

$$\left. \begin{array}{l} (G \in RO(Y, f(x))) (x \notin f^{-1}[G]) \\ \text{Hypothesis} \end{array} \right\} \Rightarrow (\exists U \in e\theta O(X, x))(f[U] \subset G) \\ \Rightarrow \left. \begin{array}{l} (\exists U \in e\theta O(X, x))(x \in U \subset f^{-1}[G]) \\ \text{Lemma2.2} \end{array} \right\} \Rightarrow \\ \Rightarrow \left(\bigcup_{x \in f^{-1}[G]} U \in e\theta O(X) \right) \left(\bigcup_{x \in f^{-1}[G]} U = f^{-1}[G] \right) \Rightarrow f^{-1}[G] \in e\theta O(X).$$

(5) ⇒ (6): Let $F \in RC(Y)$. We have

$$\begin{aligned} F \in RC(Y) &\Leftrightarrow X \setminus F \in RO(Y) \\ &\Leftrightarrow f^{-1}[X \setminus F] \in e\theta O(X) \\ &\Leftrightarrow X \setminus f^{-1}[F] \in e\theta O(X) \\ &\Leftrightarrow f^{-1}[F] \in e\theta C(X). \end{aligned}$$

(6)⇒(7): Let $V \in \delta O(Y)$. We have

$$\begin{aligned} V \in \delta O(Y) &\Rightarrow X \setminus V \in \delta C(Y) \\ &\Rightarrow X \setminus V = cl_\delta(X \setminus V) \\ &\Rightarrow X \setminus V = \bigcap \{F | (W \subset F)(F \in RC(Y))\} \Big\} \Rightarrow \\ &\hspace{15em} \text{Hypothesis} \\ \Rightarrow (X \setminus V \subset F \in RC(Y) \Rightarrow f^{-1}[F] \in e\theta C(X)) &\left(f^{-1}[X \setminus V] = \bigcap_{X \setminus V \subset F \in RC(Y)} f^{-1}[F] \right) \\ &\Rightarrow f^{-1}[X \setminus V] \in e\theta C(X) \\ &\Rightarrow X \setminus f^{-1}[V] \in e\theta C(X) \\ &\Rightarrow f^{-1}[V] \in e\theta O(X). \end{aligned}$$

(7)⇒(8): Let $F \in \delta C(Y)$. We have

$$\begin{aligned} F \in \delta C(Y) &\Rightarrow X \setminus F \in \delta O(Y) \\ &\Rightarrow f^{-1}[X \setminus F] \in e\theta O(X) \\ &\Rightarrow X \setminus f^{-1}[F] \in e\theta O(X) \\ &\Rightarrow f^{-1}[F] \in e\theta C(X). \end{aligned}$$

(8)⇒(9): Let $A \subset X$. We have

$$\begin{aligned} A \subset X \Rightarrow cl_\delta(f[A]) \in \delta C(Y) &\Big\} \Rightarrow f^{-1}[cl_\delta(f[A])] \in e\theta C(X) \Big\} \Rightarrow \\ \text{Hypothesis} &\hspace{10em} x \notin f^{-1}[cl_\delta(f[A])] \\ \Rightarrow (\exists U \in eO(X, x))(e-cl(U) \cap f^{-1}[cl_\delta(f[A])] = \emptyset). \\ \Rightarrow (\exists U \in eO(X, x))(e-cl(U) \cap A = \emptyset). \\ \Rightarrow x \notin e-cl_\theta(A). \end{aligned}$$

Then $e-cl_\theta(A) \subset f^{-1}[cl_\delta(f[A])] \Rightarrow f^{-1}[e-cl_\theta(A)] \subset cl_\delta(f[A])$.

(9)⇒(10): Let $B \subset Y$. We have

$$B \subset Y \Rightarrow f^{-1}[B] \subset X \Big\} \Rightarrow f[e-cl_\theta(f^{-1}[B])] \subset cl_\delta(f[f^{-1}[B]]) \subset cl_\delta(B) \Rightarrow e-cl_\theta(f^{-1}[B]) \subset f^{-1}[cl_\delta(B)]$$

Hypothesis

(10)⇒(11): Let $B \subset Y$. We have

$$\begin{aligned} B \subset Y \Rightarrow cl(int(cl(B))) \in RC(Y) &\Rightarrow cl(int(cl(B))) \in \delta C(Y) \Big\} \Rightarrow \\ &\hspace{15em} cl(int(cl(B))) \subset cl(B) \\ \Rightarrow e-cl_\theta(f^{-1}[cl(int(cl(B)))]) \subset f^{-1}[cl_\delta(cl(int(cl(B))))] &\subset f^{-1}[cl_\delta(cl_\delta \\ \Rightarrow e-cl_\theta(f^{-1}[cl(int(cl(B)))]) \subset f^{-1}[cl_\delta(int(cl(B)))] &= f^{-1}[cl(int(cl(B)))] \\ \Rightarrow e-cl_\theta(f^{-1}[cl(int(cl(B)))]) \subset f^{-1}[cl(B)]. \end{aligned}$$

(11)⇒(12): Let $V \in \beta O(Y)$. We have

$$V \in \beta O(Y) \stackrel{[2]}{\Rightarrow} cl(V) \in RC(Y) \Big\} \Rightarrow$$

Hypothesis

$$\Rightarrow e-cl_\theta(f^{-1}[V]) \subset e-cl_\theta(f^{-1}[cl(V)]) = e-cl_\theta(f^{-1}[cl(int(cl(V)))]) \subset f^{-1}[cl(V)].$$

(12)⇒(13): This is obvious since every semiopen set is β -open.

(13)⇒(14): Let $V \in \beta O(Y)$. We have

$$V \in \beta O(Y) \xrightarrow{\text{Lemma 2.6}} \alpha-cl(V) \in SO(Y) \left. \vphantom{V \in \beta O(Y)} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array}$$

$$\begin{aligned} &\Rightarrow e-cl_\theta(f^{-1}[V]) \subset e-cl_\theta(f^{-1}[\alpha-cl(V)]) \subset e-cl_\theta(f^{-1}[cl(\alpha-cl(V))]) \subset f^{-1}[cl(V)] \\ &\Rightarrow e-cl_\theta(f^{-1}[V]) \subset f^{-1}[cl(V)] \stackrel{\text{Lemma 2.3}}{=} f^{-1}[\alpha-cl(V)]. \end{aligned}$$

(14)⇒(15): Let $V \in SO(Y)$. We have

$$V \in SO(Y) \Rightarrow V \in \beta O(Y) \left. \vphantom{V \in SO(Y)} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array}$$

$$V \in SO(Y) \stackrel{\text{Lemma 2.6}}{\implies} \alpha-cl(V) = pcl(V) \left. \vphantom{V \in SO(Y)} \right\} \Rightarrow e-cl_\theta(f^{-1}[V]) \subset f^{-1}[pcl(V)].$$

(15)⇒(16): Let $V \in C(Y)$. We have

$$V \in C(Y) \Rightarrow cl(int(V)) \in SO(Y) \left. \vphantom{V \in C(Y)} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array} \Rightarrow e-cl_\theta(f^{-1}[cl(int(V))]) \subset f^{-1}[pcl(int(cl(V)))] \subset f^{-1}[V].$$

(16)⇒(17): Let $V \in \sigma$. We have

$$V \in \sigma \Rightarrow cl(V) \in C(Y) \left. \vphantom{V \in \sigma} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array} \Rightarrow e-cl_\theta(f^{-1}[cl(int(cl(V)))] \subset f^{-1}[cl(V)] \Rightarrow e-cl_\theta(f^{-1}[cl(V)]) \subset f^{-1}[cl(V)].$$

(17)⇒(18): Let $V \in \sigma$. We have

$$V \in \sigma \Rightarrow Y \setminus cl(V) \in \sigma \stackrel{\text{Lemmas 2.1,2.5}}{\implies}$$

$$\Rightarrow X \setminus e-int_\theta(f^{-1}[scl(V)]) = e-cl_\theta(f^{-1}[Y \setminus int(cl(V))]) = e-cl_\theta(f^{-1}[cl(Y \setminus cl(V))]) \left. \vphantom{\Rightarrow} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array}$$

$$\begin{aligned} &\Rightarrow X \setminus e-int_\theta(f^{-1}[scl(V)]) \subset f^{-1}[Y \setminus cl(V)] \subset X \setminus f^{-1}[V] \\ &\Rightarrow f^{-1}[V] \subset e-int_\theta(f^{-1}[scl(V)]). \end{aligned}$$

(18)⇒(19): Let $V \in PO(Y)$. We have

$$V \in PO(Y) \Rightarrow scl(V) = int(cl(V)) \left. \vphantom{V \in PO(Y)} \right\} \begin{array}{l} \text{Lemma 2.1} \\ \text{Hypothesis} \\ \Rightarrow \end{array}$$

$$\Rightarrow f^{-1}[V] \subset f^{-1}[scl(V)] \subset e-int_\theta(f^{-1}[scl(V)]) \subset e-int_\theta(f^{-1}[int(cl(V))]).$$

(19)⇒(20) and (20)⇒(21) are clear.

(21)⇒(22): Let $x \in X$ and $V \in O(Y_S, f(x))$. We have

$$(x \in X) (V \in O(Y_S, f(x))) \Rightarrow (\exists G \in RO(Y))(f(x) \in G \subset V) \left. \vphantom{(x \in X)} \right\} \begin{array}{l} \text{Hypothesis} \\ \Rightarrow \end{array} \Rightarrow x \in f^{-1}[G] \subset e-int_\theta(f^{-1}[G])$$

$$\Rightarrow f^{-1}[G] \in e\theta O(X)$$

$$\begin{aligned} &\stackrel{\text{Lemma 2.2}}{\Rightarrow} (\exists U \in eO(X, x))(e-cl(U) \subset f^{-1}[G]) \\ &\Rightarrow (\exists U \in eO(X, x))(f[e-cl(U)] \subset G \subset V). \end{aligned}$$

$$\begin{aligned} & \left. \begin{aligned} (22) \Rightarrow (1): \text{ Let } V \in O(Y) \text{ and } x \in f^{-1}[V]. \text{ We have} \\ (V \in O(Y)) (x \in f^{-1}[V]) \Rightarrow f(x) \in V \subset \text{int}(cl(V)) \in \sigma \\ \text{Hypothesis} \end{aligned} \right\} \Rightarrow (\exists U \in eO(X, x))(e-cl(U) \subset f^{-1}[\text{int}(cl(V))]) \\ & \Rightarrow (\exists U \in eO(X, x))(f[e-cl(U)] \subset \text{int}(cl(V))). \end{aligned}$$

□

Definition 3.3. Let A be a subset of a topological space X . The e - θ -frontier of A is defined by $e-Fr_{\theta}(A) = e-cl_{\theta}(A) \setminus e-int_{\theta}(A)$.

Theorem 3.4. The set of all points $x \in X$ at which a function $f : X \rightarrow Y$ is not a.st. θ .e.c. coincides with the union of the e - θ -frontiers of the inverse images of regular open sets of Y containing $f(x)$.

Proof. Let $A := \{x \mid f \text{ is not a.st.}\theta\text{.e.c. at a point } x \text{ of } X\}$. Then

$$\begin{aligned} x \in A &\Rightarrow (\exists V \in RO(Y, f(x)))(\forall U \in eO(X, x))(f[e-cl(U)] \not\subset V) \\ &\Rightarrow (\exists V \in RO(Y, f(x)))(\forall U \in eO(X, x))(e-cl(U) \not\subset f^{-1}[V]) \\ &\Rightarrow (\exists V \in RO(Y, f(x)))(\forall U \in eO(X, x))(e-cl(U) \cap (X \setminus f^{-1}[V]) \neq \emptyset) \\ &\Rightarrow x \in e-cl_{\theta}(X \setminus f^{-1}[V]) \\ &\Rightarrow x \in X \setminus e-int_{\theta}(f^{-1}[V]) \\ &\Rightarrow x \notin e-int_{\theta}(f^{-1}[V]), \end{aligned} \tag{3.3}$$

$$f(x) \in V \Rightarrow x \in f^{-1}[V] \subset e-cl_{\theta}(f^{-1}[V]) \Rightarrow x \in e-cl_{\theta}(f^{-1}[V]) \tag{3.4}$$

(3.3), (3.4) $\Rightarrow x \in e-Fr_{\theta}(f^{-1}[V])$.

Then we have $A \subset \bigcup \{e-Fr_{\theta}(f^{-1}[V]) \mid f(x) \in V \in RO(Y)\}$.

$$\begin{aligned} & \left. \begin{aligned} x \notin A \Rightarrow f \text{ is a.st.}\theta\text{.e.c. at } x \\ f(x) \in V \in RO(Y) \end{aligned} \right\} \Rightarrow x \in f^{-1}[V] \in e\theta O(X) \\ & \Rightarrow x \in e-int_{\theta}(f^{-1}[V]) \\ & \Rightarrow x \notin e-Fr_{\theta}(f^{-1}[V]) \\ & \Rightarrow x \notin \bigcup \{e-Fr_{\theta}(f^{-1}[V]) \mid f(x) \in V \in RO(Y)\}. \end{aligned}$$

Then we have $\bigcup \{e-Fr_{\theta}(f^{-1}[V]) \mid f(x) \in V \in RO(Y)\} \subset A$. □

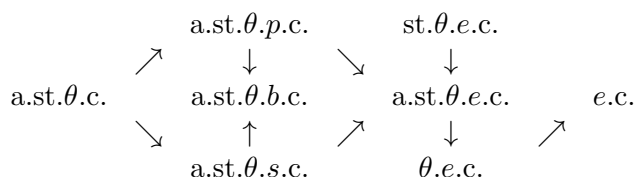
4. Comparisons and Some Properties

Definition 4.1. A function $f : X \rightarrow Y$ is called almost strongly θ -continuous [17] (resp. almost strongly θ -semicontinuous [4], almost strongly θ -precontinuous [21], almost strongly θ - b -continuous [18]), if for each $x \in X$ and each open set V containing $f(x)$, there is an open (resp. semi-open, preopen, b -open) set U containing x such that $f[cl(U)] \subset \text{int}(cl(V))$ (resp. $f[scl(U)] \subset \text{int}(cl(V))$, $f[pcl(U)] \subset \text{int}(cl(V))$, $f[bcl(U)] \subset \text{int}(cl(V))$).

Definition 4.2. A function $f : X \rightarrow Y$ is called strongly θ - e -continuous [19] (resp. e -continuous [8]) if for each $x \in X$ and each open set V containing $f(x)$, there is an e -open set U containing x such that $f[e-cl(U)] \subset V$ (resp. $f[U] \subset V$).

Definition 4.3. A function $f : X \rightarrow Y$ is called θ - e -continuous [11] if for each $x \in X$ and each open set V containing $f(x)$, there is an e -open set U containing x such that $f[e-cl(U)] \subset cl(V)$.

Remark 4.4. From Definitions 4.1, 4.2 and 4.3, we have the following diagram.



However, none of these implications is reversible as shown by the following examples.

Example 4.5. Let $X = \{a, b, c, d\}$, $\tau = \{\emptyset, X, \{c\}, \{a, b\}, \{a, b, c\}\}$ and $\sigma = \{\emptyset, X, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{a, b, c\}, \{a, c, d\}\}$.

- (a) Define the function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = f(b) = a$, $f(c) = f(d) = c$. Then f is a.st. θ .e.c. on X , but it is not a.st. θ .p.c. at the point d of X .
- (b) Define the function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = a$, $f(b) = c$, $f(c) = f(d) = d$. Then f is a.st. θ .e.c. on X , but it is not a.st. θ .s.c. at the point a of X .

Example 4.6. Let $X = \{a, b, c, d\}$, $\tau = \{\emptyset, X, \{a\}, \{c\}, \{a, c\}, \{c, d\}, \{a, c, d\}\}$ and $\sigma = \{\emptyset, X, \{c\}, \{d\}, \{c, d\}, \{a, c, d\}, \{b, c, d\}\}$.

- (a) Define a function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = f(c) = f(d) = a$, $f(b) = c$. Then f is θ .e.c. on X , but it is not a.st. θ .e.c. at the point b of X .
- (b) Define a function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = f(b) = f(d) = d$, $f(c) = a$. Then f is a.st. θ .e.c. on X , but it is not a.st. θ .b.c. at the point d of X .

Example 4.7. Let $X = \{a, b, c, d\}$, $\tau = \{\emptyset, X, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{a, b, c\}, \{a, c, d\}\}$ and $\sigma = \{\emptyset, X, \{a\}, \{c\}, \{a, c\}, \{c, d\}, \{a, c, d\}\}$. Define a function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = f(b) = b$, $f(c) = d$, $f(d) = c$. Then f is a.st. θ .e.c. on X , but it is not st. θ .e.c. at the point d of X .

Example 4.8. Let $X = \{a, b, c, d\}$, $\tau = \{\emptyset, X, \{a\}, \{c\}, \{a, c\}, \{c, d\}, \{a, c, d\}\}$ and $\sigma = \{\emptyset, X, \{c\}, \{d\}, \{c, d\}, \{a, c, d\}, \{b, c, d\}\}$. Define a function $f : (X, \tau) \rightarrow (X, \sigma)$ by $f(a) = f(d) = a$, $f(b) = f(c) = c$. Then f is a.st. θ .b.c. on X , but it is not a.st. θ .e.c. at the point c of X .

The family of regular open sets of a space (X, τ) forms a base for a smaller topology τ_s on X , called semi-regularization of τ . The space (X, τ) is said to be semi-regular if $\tau_s = \tau$ [14].

A space (X, τ) is called almost regular [23] if for any regular open set $U \subset X$ and each point $x \in U$, there is a regular open set V of X such that $x \in V \subset cl(V) \subset U$.

Theorem 4.9. Let $f : X \rightarrow Y$ be a function. Then the following statements hold:

- (a) If $f : X \rightarrow Y$ e.c. and Y is almost regular, then f is a.st. θ .e.c.
- (b) If $f : X \rightarrow Y$ is a.st. θ .e.c. and Y is semi-regular, then f is st. θ .e.c.

Proof. (a) Let f be e.c. and Y almost regular. We have

$$\left. \begin{array}{l} (x \in X) (V \in RO(Y, f(x))) \\ Y \text{ is almost regular} \end{array} \right\} \Rightarrow \left. \begin{array}{l} (\exists W \in RO(Y, f(x))) (W \subset cl(W) \subset V) \\ f \text{ is e.c.} \end{array} \right\} \Rightarrow \\
 \Rightarrow \left. \begin{array}{l} (\exists U \in eO(X, x)) (f[U] \subset W \Rightarrow U \subset f^{-1}[W]) \\ y \notin cl(W) \Rightarrow (\exists G \in \mathcal{U}(y)) (G \cap W = \emptyset) \Rightarrow f^{-1}[G] \cap f^{-1}[W] = \emptyset \end{array} \right\} \Rightarrow f^{-1}[G] \cap U = \emptyset \dots (1)$$

$$\left. \begin{array}{l} G \in \mathcal{U}(y) \\ f \text{ is e.c.} \end{array} \right\} \Rightarrow f^{-1}[G] \in eO(X) \dots (2)$$

$$(1), (2) \Rightarrow f^{-1}[G] \cap e-cl(U) = \emptyset \Rightarrow G \cap f[e-cl(U)] = \emptyset \Rightarrow y \notin f[e-cl(U)].$$

(b) Let f be a.s.t.θ.e.c. and Y semi-regular. We have

$$\left. \begin{array}{l} (x \in X)(V \in \mathcal{U}(Y, f(x))) \\ Y \text{ is semi-regular} \end{array} \right\} \Rightarrow \left. \begin{array}{l} (\exists W \in RO(X, x))(W \subset V) \\ f \text{ is a.s.t.}\theta.e.c. \end{array} \right\} \Rightarrow (\exists W \in eO(X, x))(f[e-cl(U)] \subset W \subset V).$$

□

Theorem 4.10. *Let Y be a semi-regular space. Then $f : X \rightarrow Y$ is a.s.t.θ.e.c. if and only if $f : X \rightarrow Y$ is st.θ.e.c.*

Proof. It follows clearly from Theorem 4.9. □

Corollary 4.11 ([19]). *Let Y be a regular space. Then the following statements are equivalent for a function $f : X \rightarrow Y$:*

- (1) f is st.θ.e.c.,
- (2) f is a.s.t.θ.e.c.,
- (3) f is θ.e.c.,
- (4) f is e.c.

Recall that a space X is called submaximal if each dense subset of X is open in X . A space X is called extremally disconnected if the closure of each open subset of X is open in X . In an extremally disconnected submaximal regular space, open, preopen, semiopen, b -open and e -open sets are equivalent. Then we have the following corollary:

Corollary 4.12 ([19]). *Let X be an extremally disconnected submaximal regular space and let Y be a regular space. Then the following statements are equivalent for a function $f : X \rightarrow Y$:*

- (1) f is almost strongly θ -continuous,
- (2) f is almost strongly θ -precontinuous,
- (3) f is almost strongly θ -semicontinuous,
- (4) f is almost strongly θ - b -continuous,
- (5) f is almost strongly θ - e -continuous,
- (6) f is strongly θ - e -continuous,
- (7) f is strongly θ -continuous,
- (8) f is b -continuous,
- (9) f is e -continuous.

5. Fundamental Properties

Lemma 5.1. *Let X be a topological space and X_0 an a -open set in X . Then:*

- (a) $X_0 \cap eO(X) := \{X_0 \cap E \mid E \in eO(X)\} = eO(X_0)$.
- (b) If $A \subset X_0$ and $A \in eO(X_0)$, then $A \in eO(X)$.
- (c) If $F \subset X_0$ and $F \in eC(X_0)$, then $F \in eC(X)$.

Proof. (a) [20]

(b) Let $A \in eO(X_0)$. Then

$$\begin{aligned} A \in eO(X_0) &\stackrel{(a)}{\Rightarrow} A \in X_0 \cap eO(X) \\ &\Rightarrow (\exists E \in eO(X))(A = X_0 \cap E) \\ &\Rightarrow A \in eO(X). \end{aligned}$$

(c) Let $F \in eC(X_0)$. Then

$$F \in eC(X_0) \Rightarrow X \setminus F \in eO(X_0) \stackrel{(b)}{\Rightarrow} X \setminus F \in eO(X) \Rightarrow F \in eC(X).$$

□

Lemma 5.2. *If $A \subset X_0 \subset X$ and X_0 is an a -open set in X , then $e-cl(A) \cap X_0 = e-cl_{X_0}(A)$, where $e-cl_{X_0}(A)$ denotes the e -closure of A in the subspace X_0 .*

Proof. Let $x \in e-cl(A) \cap X_0$ and $U \in eO(X_0, x)$. We have

$$\left. \begin{aligned} (x \in e-cl(A) \cap X_0) (U \in eO(X_0, x)) &\stackrel{\text{Lemma 5.1}}{\Rightarrow} (\exists V \in eO(X, x)) (U = V \cap X_0) \\ &\left. \begin{aligned} &x \in e-cl(A) \end{aligned} \right\} \Rightarrow \\ \Rightarrow \emptyset \neq V \cap A = U \cap A &\Rightarrow x \in e-cl_{X_0}(A). \text{ Then we have } e-cl(A) \cap X_0 \subset e-cl_{X_0}(A). \\ (x \in e-cl_{X_0}(A)) (U \in eO(X, x)) &\stackrel{\text{Lemma 5.1}}{\Rightarrow} (U \cap X_0 \in eO(X, x)) (\emptyset \neq A \cap (U \cap X_0) = A \cap U) \\ &\Rightarrow x \in e-cl(A) \dots (1) \\ &x \in e-cl_{X_0}(A) \subset X_0 \Rightarrow x \in X_0 \dots (2) \\ (1), (2) &\Rightarrow x \in e-cl(A) \cap X. \text{ Then we have } e-cl_{X_0}(A) \subset e-cl(A) \cap X_0. \end{aligned}$$

□

Lemma 5.3. *Let $G \subset X_0 \subset X$ and X_0 be an a -open set in X . If G is an e - θ -open set in X_0 , then G is an e - θ -open set in X .*

Proof. Let $G \in e\theta O(X_0, x)$. Then

$$\begin{aligned} G \in e\theta O(X_0, x) &\stackrel{\text{Lemma 2.2}}{\Rightarrow} (\exists U \in eO(X_0, x)) (U \subset e-cl(U) \subset G) \\ &\stackrel{\text{Lemma 2.2}}{\Rightarrow} e-cl_{X_0}(U) \in eC(X_0) \\ &\stackrel{\text{Lemma 5.1}}{\Rightarrow} (U \in eO(X)) (e-cl_{X_0}(U) \in eC(X)) \\ &\Rightarrow x \in U \subset e-cl(U) \subset e-cl(e-cl_{X_0}(U)) = e-cl_{X_0}(U) \subset G \\ &\Rightarrow x \in e-int_\theta(G). \end{aligned}$$

□

Lemma 5.4. *If X_0 is an a -open set and U is an e - θ -open set in X , then $U \cap X_0$ is an e - θ -open set in the relative topology of X_0 .*

Proof. Let X_0 be an a -open set in X and $U \in e\theta O(X)$. Then

$$\left. \begin{aligned} x \in U \cap X_0 &\Rightarrow (x \in U) (x \in X_0) \\ &\left. \begin{aligned} &U \in e\theta O(X) \end{aligned} \right\} \stackrel{\text{Lemma 2.2}}{\Rightarrow} (\exists T \in eO(X, x)) (e-cl(T) \subset U) \\ &\stackrel{\text{Lemma 5.1}}{\Rightarrow} (T \cap X_0 \in eO(X_0, x)) (T \cap X_0 \subset e-cl(T) \cap X_0 \subset U \cap X_0) \\ &\stackrel{\text{Lemma 5.2}}{\Rightarrow} (T \cap X_0 \in eO(X_0, x)) (T \cap X_0 \subset e-cl_{X_0}(T \cap X_0)) \\ &= e-cl(T \cap X_0) \cap X_0 \subset e-cl(T) \cap X_0 \subset U \cap X_0 \\ &\Rightarrow x \in e-int_\theta(U \cap X_0). \end{aligned}$$

□

Corollary 5.5. *If X_0 is an a -open set and U is an e - θ -open set in X , then $U \cap X_0$ is an e - θ -open set in X .*

Theorem 5.6. *Let $\{U_\alpha \mid \alpha \in \Lambda\}$ be an a -open cover of a topological space X . A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is a.st. θ .e.c. if and only if the restriction $f|_{U_\alpha} : (U_\alpha, \tau_{U_\alpha}) \rightarrow (Y, \sigma)$ is a.st. θ .e.c. for each $\alpha \in \Lambda$.*

Proof. Necessity. Let f be a.st. θ .e.c. and $\alpha_0 \in \Lambda$ and $x \in U_{\alpha_0}$. Then

$$\left. \begin{aligned} (f(x) \in V \in \sigma) \text{ (} f \text{ a.st.}\theta\text{.e.c.)} &\Rightarrow (\exists G \in eO(X, x)) (f[e-cl(G)] \subset \text{int}(cl(V))) \\ &W := G \cap U_{\alpha_0} \end{aligned} \right\} \Rightarrow$$

$$\xrightarrow{\text{Lemma 5.1,5.2}} (x \in W \in eO(U_{\alpha_0})) (e-cl_{U_{\alpha_0}}(W) \subset e-cl(W))$$

$$\Rightarrow (W \in eO(U_{\alpha_0}, x)) (f|_{U_{\alpha_0}} [e-cl_{U_{\alpha_0}}(W)] = f [e-cl_{U_{\alpha_0}}(W)] \subset f [e-cl(W)] \subset \text{int}(cl(V))).$$

Sufficiency. Let $f|_{U_\alpha}$ be a.st. θ .e.c. for all $\alpha \in \Lambda$ and $V \in RO(Y)$. Then

$$\left. \begin{aligned} V \in RO(Y) \\ f|_{U_\alpha} \text{ is a.st.}\theta\text{.e.c.} \end{aligned} \right\} \xrightarrow{\text{Theorem 3.2}} (\forall \alpha \in \Lambda) ((f|_{U_\alpha})^{-1}[V] \in e\theta O(U_\alpha))$$

$$\xrightarrow{\text{Lemma 5.3}} (\forall \alpha \in \Lambda) ((f|_{U_\alpha})^{-1}[V] \in e\theta O(X)) \dots(1)$$

$$\Rightarrow f^{-1}[V] = f^{-1}[V] \cap X = f^{-1}[V] \cap \left(\bigcup_{\alpha \in \Lambda} U_\alpha \right) = \bigcup \{f^{-1}[V] \cap U_\alpha \mid \alpha \in \Lambda\}$$

$$\Rightarrow f^{-1}[V] = \bigcup \{(f|_{U_\alpha})^{-1}[V] \mid \alpha \in \Lambda\} \dots(2)$$

$$(1), (2) \Rightarrow f^{-1}[V] \in e\theta O(X). \quad \square$$

Definition 5.7. A function $f : X \rightarrow Y$ is called an R -map [6] if the preimage of every regular open subset of Y is regular open in X .

Definition 5.8. A function $f : X \rightarrow Y$ is called δ -continuous [16] if for each $x \in X$ and each open set V containing $f(x)$, there is an open set U containing x such that $f[\text{int}(cl(U))] \subset \text{int}(cl(V))$.

Theorem 5.9. *Let $f : X \rightarrow Y$ and $g : Y \rightarrow Z$ be two functions. Then:*

- (1) *If f is a.st. θ .e.c. and g is an R -map, then $g \circ f$ is a.st. θ .e.c.*
- (2) *If f is a.st. θ .e.c. and g is δ -continuous, then $g \circ f$ is a.st. θ .e.c.*

Proof. Clear. □

Theorem 5.10. *Let $f : X \rightarrow Y$ be a function and $g : Y \rightarrow Z$ an injective R -map which preserves regular open sets. Then f is a.st. θ .e.c. if and only if $g \circ f$ is a.st. θ .e.c.*

Proof. Necessity. It follows from Theorem 5.9.

Sufficiency. Let $g \circ f$ be a.st. θ .e.c. and let g be an injective R -map which preserves regular open sets.

$$\left. \begin{aligned} V \in RO(Y) &\xrightarrow{\text{Hypothesis}} g[V] \in RO(Z) \\ &g \text{ is } R\text{-map and injective} \end{aligned} \right\} \Rightarrow V = g^{-1}[g[V]] \in RO(Y)$$

$$\Rightarrow f^{-1}[V] = f^{-1}[g^{-1}[g[V]]] = (g \circ f)^{-1}[g[V]] \left. \begin{aligned} &g \circ f \text{ is a.st.}\theta\text{.e.c.} \end{aligned} \right\} \Rightarrow f^{-1}[V] \in e\theta O(X). \quad \square$$

Theorem 5.11. *Let $\{Y_\alpha \mid \alpha \in \Lambda\}$ be a family of spaces. If a function $f : X \rightarrow \Pi Y_\alpha$ is a.st. θ .e.c., then $P_\alpha \circ f : X \rightarrow Y_\alpha$ is a.st. θ .e.c. for each $\alpha \in \Lambda$, where P_α is the projection of ΠY_α onto Y_α .*

Proof. This is obvious from Theorem 5.9 because every open continuous surjection P_α is an R -map. □

6. Separation Axioms

Definition 6.1. A space X is called almost e -regular [11] if for any regular closed set $F \subset X$ and any point $x \in X \setminus F$, there exist disjoint e -open sets U and V such that $x \in U$ and $F \subset V$.

Theorem 6.2. The following statements are equivalent for a space X :

- (1) X is almost e -regular,
- (2) for each $x \in X$ and for each regular open set U of X containing x , there exists $V \in eO(X)$ such that $x \in V \subset e-cl(V) \subset U$,
- (3) for each regular closed set F of X , $F = \bigcap \{e-cl(V) \mid F \subset V \text{ and } V \in eO(X)\}$,
- (4) for each subset $A \subset X$ and each regular closed set F such that $A \cap F = \emptyset$, there exist disjoint $U, V \in eO(X)$ such that $A \cap U \neq \emptyset$ and $F \subset V$,
- (5) for each subset $A \subset X$ and each regular open set U such that $A \cap U \neq \emptyset$, there exists $W \in eO(X)$ such that $A \cap W \neq \emptyset$ and $e-cl(W) \subset U$.

Proof. It can be proved directly. □

Theorem 6.3. If a continuous function $f : X \rightarrow X$ is a.st.θ.e.c., then X is almost e -regular.

Proof. Let f be the identity function. Then f is continuous and a.st.θ.e.c. so,

$$\left. \begin{array}{l} x \in U \in RO(X) \\ f \text{ is identity and a.st.}\theta.e.c. \end{array} \right\} \Rightarrow x \in f^{-1}[U] = U \in e\theta O(X)$$

$$\xrightarrow{\text{Lemma 2.2}} (\exists V \in eO(X, x))(V \subset e-cl(V) \subset U).$$

□

Theorem 6.4. An R -map $f : X \rightarrow X$ is a.st.θ.e.c. if and only if X is almost e -regular.

Proof. Necessity. Obvious.

Sufficiency. Let f be an R -map and X be almost e -regular.

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \\ f \text{ is } R\text{-map} \end{array} \right\} \Rightarrow \left. \begin{array}{l} (x \in f^{-1}[V] \in RO(X)) \\ X \text{ is almost } e\text{-regular} \end{array} \right\} \xrightarrow{\text{Theorem 6.2}}$$

$$\Rightarrow (\exists U \in eO(X, x))(e-cl(U) \subset f^{-1}[V])$$

$$\Rightarrow (\exists U \in eO(X, x))(f[e-cl(U)] \subset V).$$

□

Definition 6.5. A space is called e -regular [19] if for any closed set $F \subset X$ and any point $x \in X \setminus F$, there exist disjoint e -open sets U and V such that $x \in U$ and $F \subset V$.

Definition 6.6. A function $f : X \rightarrow Y$ is called almost continuous [24] if the preimage of every regular open subset of Y is open in X .

Theorem 6.7. If $f : X \rightarrow Y$ is almost continuous and X is e -regular, then f is a.st.θ.e.c.

Proof. Let $x \in X$ and let $V \in RO(Y, f(x))$. Then

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \\ f \text{ is almost continuous} \end{array} \right\} \Rightarrow \left. \begin{array}{l} x \in f^{-1}[V] \in \tau \\ X \text{ is } e\text{-regular} \end{array} \right\} \stackrel{[19]}{\Rightarrow}$$

$$\Rightarrow (\exists U \in eO(X, x))(e-cl(U) \subset f^{-1}[V])$$

$$\Rightarrow (\exists U \in eO(X, x))(f[e-cl(U)] \subset V).$$

□

Theorem 6.8. Let $f : X \rightarrow Y$ be a function and let $g : X \rightarrow X \times Y$, given by $g(x) = (x, f(x))$ for each $x \in X$ be graph function. Then g is a.st.θ.e.c. if and only if f is a.st.θ.e.c. and X is almost e -regular.

Proof. Necessity. Let $x \in X$ and let $V \in RO(Y, f(x))$. Then

$$\left. \begin{array}{l} (x \in X)(V \in RO(Y, f(x))) \Rightarrow g(x) = (x, f(x)) \in X \times V \\ X \times V \in RO(X \times Y) \\ g \text{ is a.st.}\theta\text{.e.c.} \end{array} \right\} \Rightarrow (\exists U \in eR(X, x))(g[U] \subset X \times V)$$

$$\Rightarrow (\exists U \in eR(X, x))(f[U] \subset V). \text{ Then } f \text{ is a.st.}\theta\text{.e.c.}$$

$$\left. \begin{array}{l} U \in RO(X, x) \Rightarrow g(x) \in U \times Y \in RO(X \times Y) \\ g \text{ is a.st.}\theta\text{.e.c.} \end{array} \right\} \Rightarrow (\exists W \in eO(X, x))(g[e-cl(W)] \subset U \times Y)$$

$$\Rightarrow (\exists W \in eO(X, x))(W \subset e-cl(W) \subset U). \text{ Then } X \text{ is almost } e\text{-regular.}$$

Sufficiency. Let $x \in X$ and let $V \in RO(X \times Y, g(x))$. Then

$$\left. \begin{array}{l} (x \in X)(V \in RO(X \times Y, g(x))) \Rightarrow (\exists V_1 \in RO(X)) (\exists V_2 \in RO(Y)) (g(x) = (x, f(x)) \in V_1 \times V_2 \subset V) \\ f \text{ is a.st.}\theta\text{.e.c.} \end{array} \right\} \Rightarrow$$

$$\Rightarrow (\exists U_0 \in eR(X, x))(f[U_0] \subset V_2) \dots (1)$$

$$U := U_0 \cap V_1 \stackrel{\text{Lemma 5.4}}{\Rightarrow} U \in e\theta O(V_1) \stackrel{\text{Lemma 5.3}}{\Rightarrow} U \in e\theta O(X) \dots (2)$$

$$(1), (2) \Rightarrow (\exists U \in e\theta O(X))(g[U] \subset U \times f[U] \subset U \times f[U_0] \subset V_1 \times V_2 \subset V). \quad \square$$

Definition 6.9. A space X is said to be:

- (1) rT_0 [10] if for each pair of distinct points x and y in X , there exists a regular open set $U \in RO(X)$ such that either $x \in U$ and $y \notin U$ or $y \in U$ and $x \notin U$.
- (2) $e-T_2$ [7] if for each pair of distinct points x and y in X , there exist e -open sets U and V of X containing x and y , respectively, such that $U \cap V = \emptyset$.

Theorem 6.10. If $f : X \rightarrow Y$ is an a.st.θ.e.c. injection and Y is rT_0 , then X is $e-T_2$.

Proof. Let $x_1, x_2 \in X$ and $x_1 \neq x_2$. Then

$$\left. \begin{array}{l} (x_1, x_2 \in X)(x_1 \neq x_2)(f \text{ is injective}) \Rightarrow f(x_1) \neq f(x_2) \\ Y \text{ is } rT_0 \end{array} \right\} \Rightarrow$$

$$\Rightarrow (\exists V \in RO(Y, f(x_1))) (\exists W \in RO(Y, f(x_2))) (f(x_1) \notin W \vee f(x_2) \notin V).$$

Case I. Let $V \in RO(Y, f(x_1))$ and $f(x_2) \notin V$.

$$\left. \begin{array}{l} V \in RO(Y, f(x_1)) \\ f \text{ is a.st.}\theta\text{.e.c.} \end{array} \right\} \Rightarrow (\exists U \in eO(X, x_1))(f[e-cl(U)] \subset V) \left. \begin{array}{l} \\ f(x_2) \notin V \end{array} \right\} \Rightarrow f(x_2) \notin f[e-cl(U)]$$

$$\Rightarrow x_2 \notin e-cl(U) \Rightarrow x_2 \in X \setminus e-cl(U).$$

Case II. It can be proved similarly. □

Corollary 6.11. *If $f : X \rightarrow Y$ is an a.st.θ.e.c. injection and Y is Hausdorff, then X is $e-T_2$.*

Proof. It is obvious since every Hausdorff space is rT_0 . □

Theorem 6.12. *Let $f, g : X \rightarrow Y$ be functions and Y a Hausdorff space. If f is a.st.θ.e.c. and g is an R -map, then the set $A = \{x \in X \mid f(x) = g(x)\}$ is e -closed in X .*

Proof. Let $x \notin A$. Then

$$\left. \begin{array}{l} x \notin A \Rightarrow f(x) \neq g(x) \\ Y \text{ is Hausdorff} \end{array} \right\} \Rightarrow (\exists V_1 \in \mathcal{U}(f(x))) (\exists V_2 \in \mathcal{U}(g(x))) (V_1 \cap V_2 = \emptyset)$$

$$\Rightarrow (\exists V_1 \in \mathcal{U}(f(x))) (\exists V_2 \in \mathcal{U}(g(x))) (int(cl(V_1)) \cap int(cl(V_2)) = \emptyset) \dots (1)$$

$$\left. \begin{array}{l} int(cl(V_1)) \in RO(Y, f(x_1)) \\ f \text{ is a.st.}\theta.e.c. \end{array} \right\} \Rightarrow (\exists G \in eO(X, x)) (f[e-cl(G)] \subset int(cl(V_1))) \dots (2)$$

$$\left. \begin{array}{l} int(cl(V_2)) \in RO(Y, f(x_2)) \\ g \text{ is } R\text{-map} \end{array} \right\} \Rightarrow g^{-1}[int(cl(V_2))] \in RO(X, x) \dots (3)$$

$$U := G \cap g^{-1}[int(cl(V_2))] \stackrel{\text{Lemma 2.7}}{\Rightarrow} U \in eO(X, x) \dots (4)$$

$$(1), (2), (3), (4) \Rightarrow (U \in eO(X, x)) (U \cap A = \emptyset) \Rightarrow x \notin e-cl(A).$$

□

7. Preservation Properties

Definition 7.1. A space X is called:

- (1) nearly compact [22] (resp. nearly countable compact [9]) if every regular open cover (resp. countable regular open cover) of X has a finite subcover.
- (2) e -closed [19] (resp. countable e -closed [19]) if every cover (resp. countable cover) of X by e -open sets has a finite subcover whose e -closures cover X .

A subset A of a space X is said to be e -closed [19] (resp. N -closed [5]) relative to X if for every cover $\{V_\alpha \mid \alpha \in I\}$ of A by e -open (resp. regular open) sets of X , there exists a finite subset I_0 of I such that $A \subset \bigcup\{e-cl(V_\alpha) \mid \alpha \in I_0\}$ (resp. $A \subset \bigcup\{V_\alpha \mid \alpha \in I_0\}$).

Theorem 7.2. *If $f : X \rightarrow Y$ is an a.st.θ.e.c. function and A is e -closed relative to X , then $f[A]$ is N -closed relative to Y .*

Proof. It can be proved directly. □

Corollary 7.3. *Let $f : X \rightarrow Y$ be an a.st.θ.e.c. surjection. Then the following statements hold:*

- (1) *If X is e -closed, then Y is nearly compact.*
- (2) *If X is countable e -closed, then Y is nearly countable compact.*

Definition 7.4. The graph $G(f)$ of a function $f : X \rightarrow Y$ is said to be θ - e -closed [11] if for each $(x, y) \in (X \times Y) \setminus G(f)$, there exist $U \in eO(X, x)$ and an open set V containing y such that $(e-cl(U) \times cl(V)) \cap G(f) = \emptyset$.

Definition 7.5. The graph $G(f)$ of a function $f : X \rightarrow Y$ is said to be almost strongly e -closed if for each $(x, y) \in (X \times Y) \setminus G(f)$, there exist $U \in eO(X, x)$ and a regular open set V containing y such that $(e-cl(U) \times V) \cap G(f) = \emptyset$.

Corollary 7.6. *If the graph $G(f)$ of a function $f : X \rightarrow Y$ is θ - e -closed, then it is almost strongly e -closed.*

Lemma 7.7. *The graph $G(f)$ of a function $f : X \rightarrow Y$ is almost strongly e -closed in $X \times Y$ if and only if for each $(x, y) \in (X \times Y) \setminus G(f)$, there exist $U \in eO(X, x)$ and a regular open set V containing y such that $f[e-cl(U)] \cap V = \emptyset$.*

Proof. It follows immediately from the definition. □

Definition 7.8. The graph $G(f)$ of a function $f : X \rightarrow Y$ is said to be strongly e -closed [19] if for each $(x, y) \in (X \times Y) \setminus G(f)$, there exist $U \in eO(X, x)$ and an open set V containing y such that $(e-cl(U) \times V) \cap G(f) = \emptyset$.

It is obvious that if the graph of a function is almost strongly e -closed, then it is strongly e -closed.

Theorem 7.9. *If $f : X \rightarrow Y$ is a.st. θ .e.c. and Y is Hausdorff, then the graph $G(f)$ of f is almost strongly e -closed in $X \times Y$.*

Proof. Let $(x, y) \notin G(f)$. Then

$$\begin{aligned} & \left. \begin{array}{l} (x, y) \notin G(f) \Rightarrow y \neq f(x) \\ Y \text{ is Hausdorff} \end{array} \right\} \Rightarrow (\exists V_1 \in \mathcal{U}(Y, f(x))) (\exists V_2 \in \mathcal{U}(Y, y)) (V_1 \cap V_2 = \emptyset) \\ & \Rightarrow \left. \begin{array}{l} (\exists V_1 \in \mathcal{U}(f(x))) (\exists V_2 \in \mathcal{U}(g(x))) (int(cl(V_1)) \cap int(cl(V_2)) = \emptyset) \\ f \text{ is a.st.}\theta\text{.e.c.} \end{array} \right\} \Rightarrow \\ & \Rightarrow (\exists U \in eO(X, x))(f[e-cl(U)] \cap int(cl(V_2)) = \emptyset). \end{aligned}$$

Then $G(f)$ is almost strongly e -closed in $X \times Y$ by Lemma 7.7. □

Theorem 7.10. *If a function $f : X \rightarrow Y$ has an almost strongly e -closed graph, then $f[K]$ is δ -closed in Y for each subset K which is e -closed relative to X .*

Proof. Let f be a.st. θ .e.c. and $y \notin f[K]$. Then

$$\begin{aligned} & \left. \begin{array}{l} y \notin f[K] \Rightarrow (\forall x \in K)((x, y) \notin G(f)) \\ G(f) \text{ is almost strongly } e\text{-closed} \end{array} \right\} \xrightarrow{\text{Lemma 7.7}} (\exists U_x \in eO(X, x)) (\exists V_x \in RO(Y, y)) (f[e-cl(U_x)] \cap V_x = \emptyset) \\ & \Rightarrow \left. \begin{array}{l} (\{U_x | x \in K\} \subset eO(X)) (K \subset \bigcup \{U_x | x \in K\}) \\ K \text{ is } e\text{-closed relative to } X \end{array} \right\} \Rightarrow \\ & \Rightarrow \left. \begin{array}{l} (\exists K^* \subset K) (|K^*| < \aleph_0) (K \subset \bigcup \{e-cl(U_x) | x \in K^*\}) \\ V := \bigcap_{x \in K^*} V_x \in RO(Y, y) \end{array} \right\} \Rightarrow \\ & \Rightarrow (V \in RO(Y, y)) \left(f[K] \cap V \subset \left(\bigcup_{x \in K^*} f[e-cl(U_x)] \right) \cap V = \emptyset \right) \\ & \Rightarrow (V \in RO(Y, y)) (f[K] \cap V = \emptyset) \Rightarrow x \notin cl_\delta(f[K]). \end{aligned}$$

□

Corollary 7.11. *If $f : X \rightarrow Y$ is an a.st. θ .e.c. function and Y is Hausdorff, then $f[K]$ is δ -closed in Y for each subset K which is e -closed relative to X .*

Theorem 7.12 ([19]). *Let X be a submaximal extremally disconnected regular space and Y be a compact Hausdorff space. Then the following statements are equivalent:*

- (1) f is strongly θ - e -continuous,

- (2) $G(f)$ is strongly e -closed in $X \times Y$,
- (3) f is strongly θ -continuous,
- (4) f is continuous,
- (5) f is e -continuous.

Corollary 7.13. *Let X be a submaximal extremally disconnected regular space and Y a compact Hausdorff space. Then the following properties are equivalent:*

- (1) f is strongly θ - e -continuous,
- (2) f is almost strongly θ - e -continuous,
- (3) $G(f)$ is almost strongly e -closed in $X \times Y$,
- (4) $G(f)$ is strongly e -closed in $X \times Y$,
- (5) f is strongly θ -continuous,
- (6) f is continuous,
- (7) f is e -continuous.

Proof. (2) \Rightarrow (3): It follows from Theorem 7.9. Other implications follow from Theorem 7.12. \square

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